

CLAIMS

1. A component placement recognition mark recognizing device for recognizing recognition marks (71) for component placement that are provided corresponding to component placement positions (70) where components (80) are to be placed in a plurality of partition areas (2A) on a board (2), the component placement recognition mark recognizing device comprising:

10 a recognition camera (90) for recognizing the recognition marks straightly disposed in the plurality of areas, and

15 a moving device (5, 15) for running the recognition camera at a generally uniform velocity in a deposition direction in which the recognition marks are straightly disposed,

wherein the recognition marks are recognized with use of the recognition camera while the recognition camera is run by the moving device.

20 2. A component placement recognition mark recognizing device as claimed in claim 1, wherein the velocity at which the recognition camera is run by the moving device is a velocity obtained from a distance between adjoining recognition marks divided by time required for capture of an image of the recognition mark.

3. A component placement recognition mark recognizing device as claimed in claim 1 or 2, wherein the plurality of areas are made into one block (2A, 2B, 2C, 2D) 5 and wherein the recognition marks (71A) for component placement that are located in a confronting pair of corners of the block and in different areas are recognized with use of the recognition camera.

10 4. A component placement recognition mark recognizing method for recognizing recognition marks (71) for component placement that are provided corresponding to component placement positions (70) where components (80) are to be placed in a plurality of partition areas (2A) on 15 a board (2),

the component placement recognition mark recognizing method comprising: respectively recognizing the recognition marks straightly disposed in the plurality of areas with use of a recognition camera (90) while the 20 recognition camera is run at a generally uniform velocity in a deposition direction in which the recognition marks are straightly disposed.

25 5. A component placement recognition mark recognizing method as claimed in claim 4, wherein the

velocity at which the recognition camera is run by the moving device is a velocity obtained from a distance between adjoining recognition marks divided by time required for capture of an image of the recognition mark.

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6. A component placement recognition mark recognizing method as claimed in claim 4 or 5, wherein the recognition marks (71A) for component placement that are located in a confronting pair of corners of one block (2A, 10 2B, 2C, 2D) composed of the plurality of areas and positioned in different areas are recognized with use of the recognition camera.